

# Preliminaries

The usual

```
12 ClearAll["Global`*"]
13 Needs["xAct`xTensor`"];
14 Needs["xAct`xCoba`"];
15 Needs["xAct`TexAct`"];
16 $DefInfoQ=$UndefInfoQ=False;
17 DefManifold[M3,3,{\alpha,\beta,\gamma,\delta}];
```

# Definitions

Scalar functions and constants

```
28 DefConstantSymbol@m,M,a,\sigma,k`;
29 DefScalarFunction@v,\lambda,rs,\rho c`
```

Abbreviations et cetera

```
36 minkowskiLimit={v\rightarrow 0,\lambda\rightarrow 0};
37 kerrAbbreviations={\Sigma\rightarrow r[]^2+a^2 \ Cos[\theta[]]^2,\Delta\rightarrow r[]^2-2M r[]+a^2,curlyA\rightarrow \Sigma \ \Delta+2M r[]}
40 nBL:=CTensor[{Sqrt[g22[r[],\theta[]]/(g11[r[],\theta[]](g11[r[],\theta[]] (\mathcal{D}[rs[\theta[]],\theta[]])^2+\mathcal{D}[rs[\theta[]],\theta[]] \ \mathcal{D}[rs[\theta[]],\theta[]]))^2+(g11[r[],\theta[]] (\mathcal{D}[rs[\theta[]],\theta[]])^2-\mathcal{D}[rs[\theta[]],\theta[]] \ \mathcal{D}[rs[\theta[]],\theta[]])^2}],nWSC:=CTensor[{Sqrt[g22[r[],\theta[]]/(g11[r[],\theta[]](g11[r[],\theta[]] (\mathcal{D}[rs[\theta[]],\theta[]])^2+\mathcal{D}[rs[\theta[]],\theta[]] \ \mathcal{D}[rs[\theta[]],\theta[]]))^2+(g11[r[],\theta[]] (\mathcal{D}[rs[\theta[]],\theta[]])^2-\mathcal{D}[rs[\theta[]],\theta[]] \ \mathcal{D}[rs[\theta[]],\theta[]])^2}],nWCC:=CTensor[{Sqrt[g22[\rho[],z[]]/(g11[\rho[],z[]](g11[\rho[],z[]] (\mathcal{D}[\rho c[z[]],z[]])^2+\mathcal{D}[\rho c[z[]],z[]] \ \mathcal{D}[\rho c[z[]],z[]]))^2+(g11[\rho[],z[]] (\mathcal{D}[\rho c[z[]],z[]])^2-\mathcal{D}[\rho c[z[]],z[]] \ \mathcal{D}[\rho c[z[]],z[]])^2}]}
```

# Assumptions

```
49 \$Assumptions={v[r[],\theta[]]\in PositiveReals,v[\rho[],z[]]\in PositiveReals,\lambda[r[],\theta[]]\in Pos-
```

# The Kerr case

```
56 DefChart[BL,M3,{1,2,3},{r[],\theta[],\phi[]},ChartColor\rightarrow Blue];
57 kerrMetricBL=CTensor[{{{\Sigma/\Delta,0,0},{0,\Sigma,0},{0,0,curlyA/\Sigma \ Sin[\theta[]]^2}},{{-BL,-BL}}}/.
58 kerrMetricBL[-\mu,-v]
59 SetCMetric[kerrMetricBL,BL,SignatureOfMetric\rightarrow {3,0,0}]
60 CD3=LC[kerrMetricBL];
63 metricCoefficientsBL={g11[r[],\theta[]]\rightarrow kerrMetricBL[1,1,1],g22[r[],\theta[]]\rightarrow kerrMetricBL[2,2,2],metricCoefficientsBLfunction={g11\rightarrow ((a^2 \ Cos[\#2]^2+\#1^2)/(a^2-2 M \ \#1+\#1^2)\&),g22\rightarrow ((a^2 \ Sin[\#2]^2+\#1^2)/(a^2-2 M \ \#1+\#1^2)\&)},normalBL[\alpha]=nBL[\alpha]/.metricCoefficientsBL//FullSimplify
```

```

68 eqnBL=Simplify[-CD3[-α]@normalBL[α]==0,$Assumptions]/.r[]→rs[θ[]]
69 H=Simplify[1/2* -CD3[-α]@normalBL[α],$Assumptions]/.r[]→rs[θ[]];
72 UnsetCMetric[kerrMetricBL]
73 CD3=.
```

## The general Weyl case with spherical Weyl coordinates

```

80 DefChart[wsc,M3,{1,2,3},{r[],θ[],φ[]},ChartColor→Green];
83 weylWSC=CTensor[{{Exp[-2*ν]*Exp[2*λ],0,0},{0,r[]^2Exp[-2*ν]*Exp[2*λ],0},{0,0,r
84 weylWSC[-μ,-ν]
85 SetCMetric[weylWSC,wsc,SignatureOfMetric→{3,0,0}]
86 CD3=LC[weylWSC];
89 metricCoefficientsWSC={g11[r[],θ[]]→weylWSC[1,1,1],g22[r[],θ[]]→weylWSC[1,2,2]
90 metricCoefficientsWSCfunction={g11→(Exp[2(λ[#1,#2]-ν[#1,#2])]&),g22→(#1^2Exp[2
91 normalWSC[α]=nWSC[α]/.metricCoefficientsWSC//FullSimplify
94 eqnWSC=Simplify[-CD3[-α]@normalWSC[α]==0,r[]∈PositiveReals]/.r[]→rs[θ[]]
97 UnsetCMetric[weylWSC]
98 CD3=.
```

## The general Weyl case with cylindrical Weyl coordinates

```

105 DefChart[wcc,M3,{1,2,3},{ρ[],z[],φ[]},ChartColor→Red];
108 weylWCC=CTensor[{{Exp[-2*ν]*Exp[2*λ],0,0},{0,Exp[-2*ν]*Exp[2*λ],0},{0,0,ρ[]^2Exp
109 weylWCC[-μ,-ν]
110 SetCMetric[weylWCC,wcc,SignatureOfMetric→{3,0,0}]
111 CD3=LC[weylWCC];
114 metricCoefficientsWCC={g11[ρ[],z[]]→weylWCC[1,1,1],g22[ρ[],z[]]→weylWCC[1,2,2]
115 metricCoefficientsWCCfunction={g11→(Exp[2(λ[#1,#2]-ν[#1,#2])]&),g22→(Exp[2(λ[#
116 normalWCC[α]=nWCC[α]/.metricCoefficientsWCC//FullSimplify
119 eqnWCC=Simplify[-CD3[-α]@normalWCC[α]==0,$Assumptions]/.ρ[]→ρc[z[]]
```

## The Majumdar-Papapetrou disc case

```

126 νλMajumdarPapapetrouDisc={ν[ρc_[z_],z_]:=(-Log[1+(2*M*EllipticK[Sqrt[((2*a*ρc[z
```

```

129 eqnMP=eqnWCC/. $\nu\lambda$ MajumdarPapapetrouDisc;
130 eqnMP=eqnWCC/. $\nu\lambda$ MajumdarPapapetrouDisc/.{Derivative[1,0][ $\nu$ ][ $\rho c[z[]]$ ],z[]}:=D[ $\nu\lambda$ M
133 UnsetCMetric[weylWCC]
134 CD3=.
```

## The Minkowski limit

```

141 eqnWSCMinkowski=eqnWSC/.minkowskiLimit//FullSimplify
142 eqnWCCMinkowski= eqnWCC/.minkowskiLimit//FullSimplify

145 catenoid[C_,u_,z_]:={C Cosh[z/C]Cos[u],C Cosh[z/C]Sin[u],z}
146 catenary[C_,z_]:= {C Cosh[z/C],0,z}
147 valuesOfC={0.5,1,1.5,2};
148 commonPlotRangeCatenoid={{-2.5,2.5}, {-2.5,2.5}, {-1.5,1.5}};
149 plotsCatenoid=Table[Show[ParametricPlot3D[catenoid[C,u,z],{u,0,2  $\pi$ },{z,-1.5,1.5}],{C,valuesOfC}];finalImageCatenoid=GraphicsGrid[{{plotsCatenoid[[1]],plotsCatenoid[[2]]},{plotsCatenoid[[3]],plotsCatenoid[[4]]}}];
150 finalImageCatenoid

153 RValues={1,4,7};
154  $\phi$ Constant=7  $\pi$ /5;
155  $\phi$ Range={0,2  $\pi$ };
156 zRange={-3,3};
157 commonPlotRange={{-10,10}, {-10,10}, zRange};
158 fromNewCoordinates[R_, $\phi$ _,z_]:={R Cosh[z/R] Cos[ $\phi$ ],R Cosh[z/R] Sin[ $\phi$ ],z}
159 catenoid[R_, $\phi$ _,z_]:= {R Cosh[z/R] Cos[ $\phi$ ],R Cosh[z/R] Sin[ $\phi$ ],z}
160 catenary[R_,z_]:= {R Cosh[z/R] Cos[ $\phi$ Constant],R Cosh[z/R] Sin[ $\phi$ Constant],z}
161 cartesianPlotCatenoids=Table[Show[ParametricPlot3D[catenoid[R, $\phi$ ,z],{ $\phi$ ,0,2  $\pi$ }],{z,zRange}],{R,RValues}];newCoordinatePlotCatenoids=Table[Show[ParametricPlot3D[{R, $\phi$ ,z},{ $\phi$ ,0,2  $\pi$ },{z,zRange}],{R,RValues}];GraphicsGrid[{{Show[{cartesianPlotCatenoids}],ImageSize->Large},Show[{newCoordinatePlotCatenoids}],ImageSize->Large}];
```

## Cross check against the paper of Krivan & Herold

```

170 eqnKHWCC=1/2(2g11[ $\rho$ [],z[]] g22[ $\rho$ [],z[]] g33[ $\rho$ [],z[]] D[ $\rho c[z[]]$ ,z[],z[]]+(D[ $\rho c[z[]]$ ],z[],z[]])+(D[ $\rho c[z[]]$ ],z[],z[])
171 (*eqnKHSC=1/2(2g11[r[], $\theta$ []] g22[r[], $\theta$ []] g33[r[], $\theta$ []] D[rs[ $\theta$ []], $\theta$ [], $\theta$ []]+(D[rs[ $\theta$ []], $\theta$ [], $\theta$ []))+(D[rs[ $\theta$ []], $\theta$ [], $\theta$ []))
172 (*eqnKHBL=1/2(2g11[r[], $\theta$ []] g22[r[], $\theta$ []] g33[r[], $\theta$ []] D[rs[ $\theta$ []], $\theta$ [], $\theta$ []]+(D[rs[ $\theta$ []], $\theta$ [], $\theta$ []))+(D[rs[ $\theta$ []], $\theta$ [], $\theta$ []))

175 eqnKHWCC-eqnWCC//Simplify
176 (*eqnKHSC-eqnWSC//Simplify*)
177 (*eqnKHBL-eqnBL*)
```

# Cylindrical solutions: Testing solution, Levi-Civita, Curzon-Chazy

```

184 DefManifold[M4,4,{b,c,d}];
187 DefChart[wcc4,M4,{0,1,2,3},{t[],ρ[],z[],φ[]},ChartColor→Red];
190 νFunction=Log[#1^2]&;
191 λFunction=Log[#1^4]&;
192 weylWCC4=CTensor[{{{-Exp[2*ν[ρ[],z[]]],0,0,0},{0,Exp[-2*ν[ρ[],z[]]]*Exp[2*λ[ρ[],z[]]]}},{{-b,-c}}];
193 SetCMetric[weylWCC4,wcc4,SignatureOfMetric→{3,1,0}]
194 CD4=LC[weylWCC4];
195
198 Einstein[CD4]==0//FullSimplify
201 UnsetCMetric[weylWCC4]
202 CD4=.
```

## Levi-Civita

```

209 νFunction=2σ Log[#1]&;
210 λFunction=4σ^2 Log[#1]+Log[k]&;
211 weylWCC4=CTensor[{{{-Exp[2*ν],0,0,0},{0,Exp[-2*ν]*Exp[2*λ],0,0},{0,0,Exp[-2*ν]*Exp[2*λ]}},{{-b,-c}}];
212 SetCMetric[weylWCC4,wcc4,SignatureOfMetric→{3,1,0}]
213 CD4=LC[weylWCC4];
214 eqnLC=eqnWCC/.{ν→νFunction,λ→λFunction}//Simplify
218 Einstein[CD4]==0//FullSimplify
221 UnsetCMetric[weylWCC4]
222 CD4=.
```

## Curzon-Chazy

```

229 νFunction=-M/Sqrt[#1^2+#2^2]&;
230 λFunction=-M^2 #1^2/(2(#1^2+#2^2)^2)&;
231 weylWCC4=CTensor[{{{-Exp[2*ν],0,0,0},{0,Exp[-2*ν]*Exp[2*λ],0,0},{0,0,Exp[-2*ν]*Exp[2*λ]}},{{-b,-c}}];
232 SetCMetric[weylWCC4,wcc4,SignatureOfMetric→{3,1,0}];
233 CD4=LC[weylWCC4];
237 Einstein[CD4]==0//FullSimplify
240 eqnWCCCC=eqnWCC/.{ν→νFunction,λ→λFunction}//Simplify//FullSimplify
```

```
243 UnsetCMetric[weylWCC4]
244 CD4=.
```

## Spherical solutions: Curzon-Chazy

```
251 DefChart[wsc4,M4,{0,1,2,3},{t[],r[],θ[],ϕ[]},ChartColor→Green];
252 νFunction=-M/#1&;
253 λFunction=-M^2Sin[#2]^2/(2#1^2)&;
254 weylWSC4=CTensor[{{{-Exp[2*ν],0,0,0},{0,Exp[-2*ν]*Exp[2*λ],0,0},{0,0,r[]^2Exp[-2*ν],0}},{-μ,-ν}}];
255 SetCMetric[weylWSC4,wsc4,SignatureOfMetric→{3,1,0}];
256 CD4=LC[weylWSC4];
257
258 Einstein[CD4]==0//FullSimplify
259
260 eqnWSCCC=eqnWSC/.{ν→νFunction,λ→λFunction}//Simplify//FullSimplify
261
262 UnsetCMetric[weylWSC4]
263 CD4=.
```

---

```
272 weylWSC4=CTensor[{{{-Exp[2*ν[r[],θ[]]],0,0,0},{0,Exp[-2*ν[r[],θ[]]]*Exp[2*λ[r[]]],0,0}},{-μ,-ν}}];
273 SetCMetric[weylWSC4,wsc4,SignatureOfMetric→{3,1,0}];
274 CD4=LC[weylWSC4];
275
276 UnsetCMetric[weylWSC4]
277 CD4=.
```

## Numerical solutions: spherical

### Kerr

Reproducing the Krivan & Harold plot

```
294 M=1;
295 ε=10^(-20);
296 odeKH=H==(-0.15)/.{θ[]→θ,a→1};
297 conditionsKH={rs[ε]==5.205,rs'[ε]==ε};
298 domain={θ,ε,π/2};

301 H
```

```

304 shtSltnKH=NDSolve[{odeKH,conditionsKH},rs, domain, Method→{"Shooting","StartingI
305 solKH=rs/.shtSltnKH;
306 plotLeft=Plot[{solKH[θ]},domain,PlotRange→{{0,π/2},{5.16,5.215}},PlotStyle→{Th
307 plotRight=Plot[H/.{rs[θ[]]→5.190,rs'[θ[]]→0,rs''[θ[]]→0,a→1,M→1}//Simplify,{θ
308 KHplot=Overlay[{plotLeft, plotRight}]

311 conditionsBL={rs[ε]==2,rs'[ε]==ε};
312 domain={θ,ε,π/2};
313 shtSltnBL=NDSolve[{eqnBL/.{θ[]→θ,a→1},conditionsBL},rs, domain, Method→{"Shootin
314 solBL=rs/.shtSltnBL;

317 plotBL1=ParametricPlot3D[{solBL[θ]*Sin[θ]*Cos[φ],solBL[θ]*Sin[θ]*Sin[φ],solBL[θ]
318 plotBL2=ParametricPlot3D[{2*Sin[θ]*Cos[φ],2*Sin[θ]*Sin[φ],solBL[θ]*Cos[θ]}, {θ,
319 plotBL=Show[{plotBL1,plotBL2},ViewPoint → {1, 2, 1}]

```

## Curzon-Chazy

```

326 eqnWSCCC

329 ε=10^(-15);
330 domain={θ,ε,π/2-ε};
331 conditionsWSCCC={rs[ε]==0.8,rs'[ε]==ε};
332 shtSltnWSCCC=NDSolve[{eqnWSCCC/.{θ[]→θ,M→1},conditionsWSCCC},rs, domain, Method→
333 solWSCCC=rs/.shtSltnWSCCC;
334 plotCCWSC1=ParametricPlot3D[
335 {solWSCCC[θ]*Sin[θ]*Cos[φ], solWSCCC[θ]*Sin[θ]*Sin[φ], solWSCCC[θ]*Cos[θ]}, {
336 {θ, 0, Pi/2}, {φ, 0, 2 Pi},
337 PlotRange → All, Mesh → True, Boxed → True, Axes → True];
338 plotCCWSC2=ParametricPlot3D[
339 {solWSCCC[θ]*Sin[θ]*Cos[φ], solWSCCC[θ]*Sin[θ]*Sin[φ], -solWSCCC[θ]*Cos[θ]}, {
340 {θ, 0, Pi/2}, {φ, 0, 2 Pi},
341 PlotRange → All, Mesh → True, Boxed → True, Axes → True];
342 Show[plotCCWSC1,plotCCWSC2]

```

## Numerical solutions: cylindrical

### Majumdar-Papapetrou

```

353 ε=10^(-20);
354 conditionsMP={ρc[ε]==1.4,ρc'[ε]==ε};
355 domain={z,-2,2};
356 shtSltnMP=NDSolve[{eqnMP/.{z[]→z,a→1,M→1},conditionsMP},ρc, domain, Method→{"Sh
357 solMP=ρc/.shtSltnMP;

```

```
360 plotMP = ParametricPlot3D[
361   {solMP[z]*Cos[ϕ], solMP[z]*Sin[ϕ], z},
362   domain, {ϕ, 0, 2 Pi},
363   PlotRange → All, Mesh → None, Boxed → True, Axes → True,
364   PlotStyle → Directive[Opacity[0.5]],
365   ColorFunction → "Rainbow", ViewPoint → {0, -5, 0}];
366 disc = ParametricPlot3D[
367   {r*Cos[ϕ], r*Sin[ϕ], 0},
368   {r, 0, 1}, {ϕ, 0, 2 Pi},
369   PlotStyle → {Black, Opacity[1], Thickness[0.05], Specularity[White, 20]},
370   Lighting → "Neutral"];
371 finalMP=Show[plotMP, disc]

374 plotMP = ParametricPlot3D[
375   {solMP[z]*Cos[ϕ], solMP[z]*Sin[ϕ], z},
376   {z, -2, 2}, {ϕ, 0, 2 Pi},
377   PlotRange → All, Mesh → None, Boxed → True, Axes → True,
378   PlotStyle → Directive[Opacity[0.5]],
379   ColorFunction → "Rainbow", ViewPoint → {1, 2, 1}];
380 disc = ParametricPlot3D[
381   {r*Cos[ϕ], r*Sin[ϕ], 0},
382   {r, 0, 1}, {ϕ, 0, 2 Pi},
383   PlotStyle → {Black, Opacity[1], Thickness[0.05], Specularity[White, 20]},
384   Lighting → "Neutral"
385 ];
386 plotMPevolve=Show[plotMP, disc]
```

```

389 conditionsMP={ρc[ε]==1.1,ρc'[ε]==ε};
390 shtSltnMP=NDSolve[{eqnMP/.{z[]→z,a→1,M→1},conditionsMP},ρc, domain,Method→{"Shc
391 solMP=ρc/.shtSltnMP;
392 plot1MP=Plot[solMP[z],{z,-2,2},Frame→True,PlotStyle→{Blue,Thin}];

393
394 conditionsMP={ρc[ε]==1.2,ρc'[ε]==ε};
395 shtSltnMP=NDSolve[{eqnMP/.{z[]→z,a→1,M→1},conditionsMP},ρc, domain,Method→{"Shc
396 solMP=ρc/.shtSltnMP;
397 plot2MP=Plot[solMP[z],{z,-2,2},Frame→True,PlotStyle→{Purple,Thin}];

398
399 conditionsMP={ρc[ε]==1.4,ρc'[ε]==ε};
400 shtSltnMP=NDSolve[{eqnMP/.{z[]→z,a→1,M→1},conditionsMP},ρc, domain,Method→{"Shc
401 solMP=ρc/.shtSltnMP;
402 plot3MP=Plot[solMP[z],{z,-2,2},Frame→True,PlotStyle→{Green,Thin}];

403
404 conditionsMP={ρc[ε]==1.6,ρc'[ε]==ε};
405 shtSltnMP=NDSolve[{eqnMP/.{z[]→z,a→1,M→1},conditionsMP},ρc, domain,Method→{"Shc
406 solMP=ρc/.shtSltnMP;
407 plot4MP=Plot[solMP[z],{z,-2,2},Frame→True,PlotStyle→{Red,Thin}];

408
409 conditionsMP={ρc[ε]==1.8,ρc'[ε]==ε};
410 shtSltnMP=NDSolve[{eqnMP/.{z[]→z,a→1,M→1},conditionsMP},ρc, domain,Method→{"Shc
411 solMP=ρc/.shtSltnMP;
412 plot5MP=Plot[solMP[z],{z,-2,2},Frame→True,PlotStyle→{Orange,Thin}];

413
414 plotMPall=Show[{plot1MP,plot2MP,plot3MP,plot4MP,plot5MP},GridLines→Automatic,F

```

## Levi-Civita

```

421 eqnLC
424 catenoid[u_,z_]:={Cosh[z]Cos[u],Cosh[z]Sin[u],z}

```

```

427  $\sigma = 0;$ 
428  $\epsilon = 10^{-7};$ 
429  $\text{conditionsLC} = \{\rho c[\epsilon] == 1, \rho c'[\epsilon] == \epsilon\};$ 
430  $\text{domain} = \{z, -2, 2\};$ 
431  $\text{shtSltnLC} = \text{NDSolve}[\{\text{eqnLC}/.z[] \rightarrow z, \text{conditionsLC}\}, \rho c, \text{domain}, \text{Method} \rightarrow \{"\text{Shooting}", "St$ 
432  $\text{solLC} = \rho c /. \text{shtSltnLC};$ 
433  $\text{plotRhocLC} = \text{Plot}[\text{solLC}[z], \text{domain}, \text{PlotStyle} \rightarrow \text{Red}];$ 
434  $\text{plotCatenary} = \text{Plot}[\text{Cosh}[z], \text{domain}, \text{PlotStyle} \rightarrow \{\text{Black}, \text{Dashed}\}];$ 
435  $\text{finalLC2} = \text{Show}[\{\text{plotRhocLC}, \text{plotCatenary}\}, \text{Frame} \rightarrow \text{True}, \text{FrameLabel} \rightarrow \{"z", "\rho(z)"\},$ 
436
437  $\text{plotLC1} = \text{ParametricPlot3D}[\{\text{solLC}[z] * \text{Cos}[\phi], \text{solLC}[z] * \text{Sin}[\phi], z\}, \text{domain}, \{\phi, 0, 2\pi\},$ 
438  $\text{PlotRange} \rightarrow \text{All}, \text{Mesh} \rightarrow \text{None}, \text{Boxed} \rightarrow \text{True}, \text{Axes} \rightarrow \text{True}, \text{ViewPoint} \rightarrow \{1, 2, 1\}];$ 
439  $\text{plotLC2} = \text{ParametricPlot3D}[\{\text{solLC}[z] * \text{Cos}[\phi], \text{solLC}[z] * \text{Sin}[\phi], -z\}, \text{domain}, \{\phi, 0, 2\pi\},$ 
440  $\text{PlotRange} \rightarrow \text{All}, \text{Mesh} \rightarrow \text{True}, \text{Boxed} \rightarrow \text{True}, \text{Axes} \rightarrow \text{True}, \text{PlotStyle} \rightarrow \text{Orange}];$ 
441  $\text{plotCatenoid} = \text{ParametricPlot3D}[\text{catenoid}[u, z], \{u, 0, 2\pi\}, \text{domain}, \text{Boxed} \rightarrow \text{True}, \text{Axes} \rightarrow \text{T$ 
442  $\text{finalLC1} = \text{Show}[\text{plotLC1}, \text{plotCatenoid}];$ 
443  $\text{image} = \text{GraphicsGrid}[\{\{\text{finalLC1}, \text{finalLC2}\}\}, \text{Spacings} \rightarrow \{50, 0.5\}, \text{ImageSize} \rightarrow 1000]$ 

```

## Curzon-Chazy

```

450  $\epsilon = 10^{-15};$ 
451  $\text{conditionsWCCCC} = \{\rho c[\epsilon] == 1, \rho c'[\epsilon] == \epsilon\};$ 
452  $\text{domain} = \{z, -2, 2\};$ 
453  $\text{shtSltnWCCCC} = \text{NDSolve}[\{\text{eqnWCCCC}/.z[] \rightarrow z, M \rightarrow 1\}, \text{conditionsWCCCC}, \rho c, \text{domain}, \text{Method} \rightarrow$ 
454  $\text{solWCCCC} = \rho c /. \text{shtSltnWCCCC};$ 
455  $\text{plotWCCCC} = \text{ParametricPlot3D}[\{\text{solWCCCC}[z] * \text{Cos}[\phi], \text{solWCCCC}[z] * \text{Sin}[\phi], z\}, \text{domain}, \{\phi, 0, 2\pi\},$ 
456  $\text{PlotRange} \rightarrow \text{All}, \text{Mesh} \rightarrow \text{True}, \text{Boxed} \rightarrow \text{True}, \text{Axes} \rightarrow \text{True}, \text{ViewPoint} \rightarrow \{1, 2, 1\}, \text{ImageSize} \rightarrow 1000];$ 
457  $\text{Show}[\text{plotWCCCC}];$ 
458  $\text{plotCC} = \text{Plot}[\text{solWCCCC}[z], \text{domain}, \text{PlotStyle} \rightarrow \text{Red}];$ 
459  $\text{plotCatenary} = \text{Plot}[\text{Cosh}[z], \text{domain}, \text{PlotStyle} \rightarrow \{\text{Black}, \text{Dashed}\}];$ 
460  $\text{finalCC} = \text{Show}[\{\text{plotCC}, \text{plotCatenary}\}, \text{Frame} \rightarrow \text{True}, \text{FrameLabel} \rightarrow \{"z", "\rho(z)"\}, \text{GridLines} \rightarrow \{\{z \rightarrow 0\}\}, \text{ImageSize} \rightarrow 1000];$ 
461  $\text{image} = \text{GraphicsGrid}[\{\{\text{plotWCCCC}, \text{finalCC}\}\}, \text{Spacings} \rightarrow \{50, 0.5\}, \text{ImageSize} \rightarrow 1000]$ 

```